

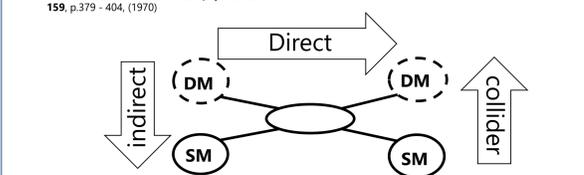
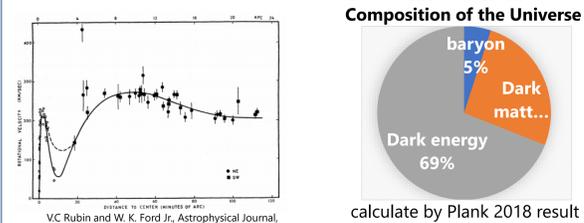
Development of High speed readout machine for directional dark matter search experiment NEWSdm

Ryuta Kobayashi (Nagoya University / Graduate school of science)

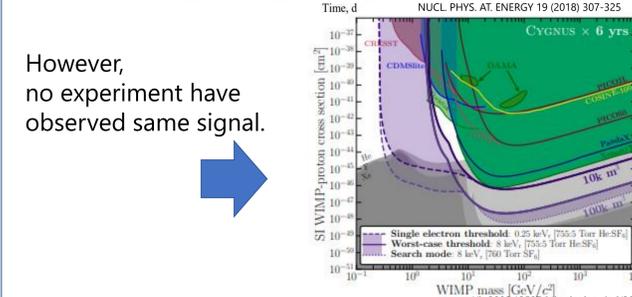
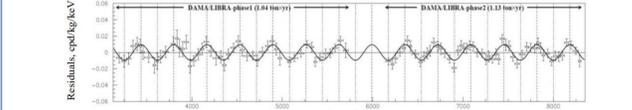
E-mail : kobayashi@flab.phys.nagoya-u.ac.jp

Introduction : Directional dark matter search experiment by solid tracking detector

Dark Matter & dark matter search



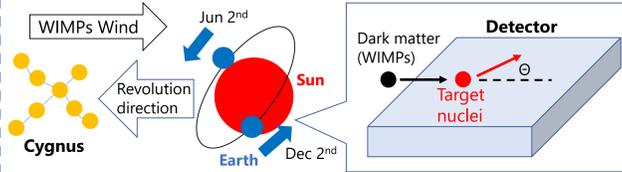
DAMA/ LIBRA experiment observed Dark matter signal !?



However, no experiment have observed same signal.

NEWSdm experiment

Directional Dark matter search experiment

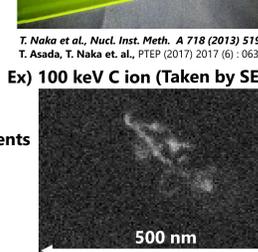
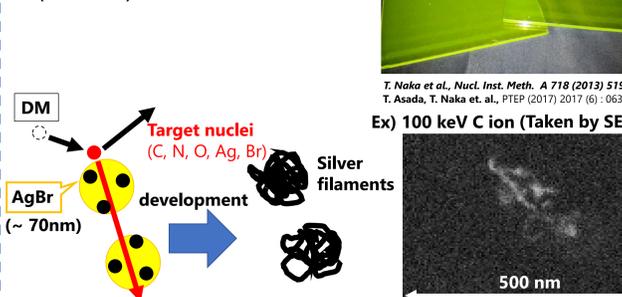


- Verification with besides seasonal variation
- statistical advantage toward seasonal variation ~O(100)
- BG rejection by directional information ex) Solar neutrino

Detector Nano Imaging Tracker : NIT

super fine grained nuclear emulsion

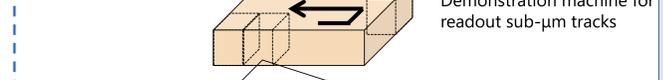
NIT is possible to record O(100 nm) tracks.



Post Track Selector : PTS

Automatic readout system for sub-μm track in NIT

How to readout ?
To get 3D information of inside NIT, Get tomographic image



Objective lens
• X100
• NA = 1.45

Resolution
optical : 191 nm (theoretical)
pixel : 55 × 55 nm

Elliptical shape analysis
Get {
• param for track identify (ellipticity)
• track direction
from shape information of optical image

Best focus selection
Remove noise come from defocus image
surface
bottom

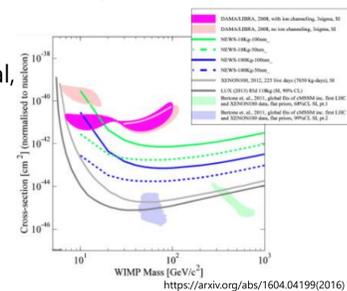
Reconstructed angle distribution of 30 keV C ion
90 degree setting, 135 degree setting, 180 degree setting

Demonstrated to readout directional information on more than 30keV C ion tracks

problem : slow scanning speed

Requirements for scanning speed

If using NIT to verify the DAMA-observed signal, at least 10 kg · year scale experiment is requested



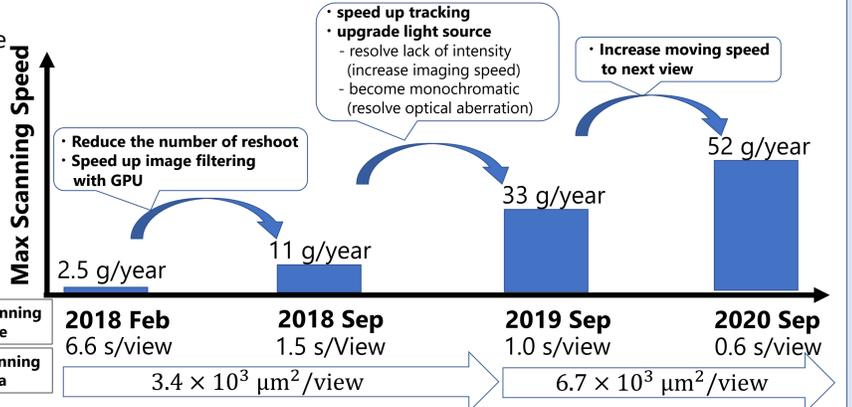
In order to execute above experiments, Ability of scanning at least 10kg of NIT par year is required

Past development

Start developing practical machine for Dark matter search since 2017



Changes in max scanning speed



Recently development : install highspped camera & speed up stage velocity

Bottleneck of scanning speed

Major part of scanning time
• Taking images
• Move to next view (return objective lens to surface position)

Detail of Scanning time [s/ view]

Taking images	Image filtering 0.1s
Move to next view	Tracking 0.1s
0.4s	0.2 s
Total : 0.6 s/view	

Speed up image taking

Install high speed camera

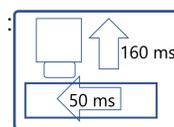
	Current camera	New camera
resolution	(W) 2048 pixel × (H)1088 pixel	(W) 1920 pixel × (H)1080 pixel
Pixel size	5.5 μm × 5.5μm	5.5 μm × 5.5μm
Shutter speed	300 fps	908 fps

Time of taking images 390 ms -> 130ms

Speed up moving to next view

Main part of moving time : Return objective lens to surface

Shorten return time : 160 ms → 50 ms



Detail of stage move time

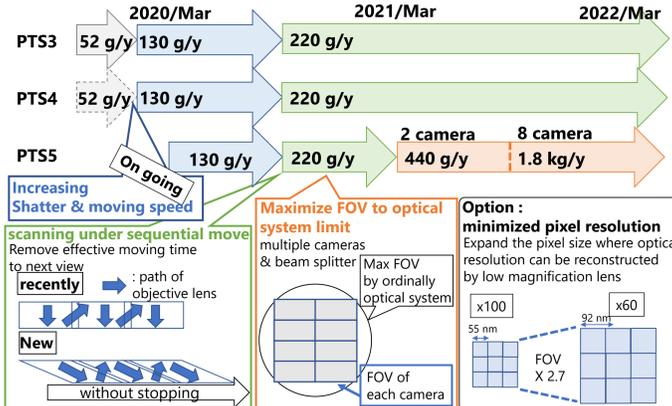
Return objective lens	160 ms
Move stage	50 ms
Acceleration	50 ms
Total	210 ms

under evaluate { stage vibration effect to optical image efficiency of new camera

By 900 fps camera + increasing stage speed
Scanning time : 0.6 s/view -> 0.25 s/view (Maximum)

Future plan : increasing scanning speed plan & event selection with machine learning

Increasing scanning speed



Event selection with machine learning

What information is contained in optical image?

• shape - size etc.)
• brightness
• color, polarization (comes from LSPR) etc.

LSPR : Localized Surface Plasmon Resonance
If $r < \lambda$
 E_0
 λ
 E_2
 $p = \epsilon_2 \alpha E_0$
 $\alpha = 4\pi r^3 \frac{\epsilon_1(\omega) - \epsilon_2}{\epsilon_1(\omega) + 2\epsilon_2}$

contain information of structure below optical resolution

conductive nanoparticles

At conventional event selection, focus on a few of the feature for ease of use.

- Ex) {
• simple shape
ex) ellipse, # of pixel
• brightness

Problem

1. The vast amount of information contained in the optical image is not being utilized.
2. Event select by track like or not

Aiming for more sophisticated event selection
With feature extraction and parameter optimization with machine learning