New Approaches to Anomaly Detection

David Shih

February 5, 2020

"Machine Learning at LHC" KMI Nagoya







Outline

- I. Motivation and setup
- 2. Conventional approaches
- 3. New approaches and the LHC Olympics 2020

I. Motivation and Setup

Tests of the Standard Model



The SM has withstood the test of time. (~50 years!)

Agreement between theory and experiment across ~ 14 orders of magnitude.

Yet we know there's new physics out there...

dark matter



neutrino masses





matter/anti-matter asymmetry

Yet we know there's new physics out there...

grand unification



hierarchy problem



$$\mathcal{L} \supset \theta \; \frac{\alpha_s}{8\pi} G_{\mu\nu} \tilde{G}^{\mu\nu}$$
$$\theta \lesssim 10^{-10}$$

flavor puzzle



strong CP problem

LHC and Big Data

At the LHC we have the highest energy collider ever built, generating copious amounts of data.

- 600 million collisions per second
- Raw data rate ~ I PB/s (I PB=10^6 GB)
- Actual data rate ~ 25 GB/s
 - Need to trigger on 1 out of 40,000 events
- ~ 10's of PB annually

There is enormous discovery potential for new physics!

Anomaly Detection at the LHC



But if there is physics beyond the SM in the data, it's likely to be rare and surrounded by SM background. Otherwise we would have seen it already!

This calls for

- sophisticated techniques to dig the signal out of the data.
- careful and precise background estimation

Anomaly Detection at the LHC



Generally, the idea is to design and optimize a discriminant sensitive to new physics vs. SM background.

Anomaly Detection at the LHC

Searches make different levels of assumptions about the signal model (e.g. gluinos, general resonance, anything ...) and the background model (SM simulation or data-driven).



from Nachman & DS 2001.04990

(a) Signal sensitivity

(b) Background specificity

2. Conventional methods

Model specific searches

$$R_S(x) = \frac{\mathcal{L}(x|S_{sim})}{\mathcal{L}(x|B_{sim})}$$

Model specific searches

$$R_S(x) = \frac{\mathcal{L}(x|S_{sim})}{\mathcal{L}(x|B_{sim})}$$

x: some set of relevant features characterizing each event (almost always binned)

Model specific searches

$$R_S(x) = \frac{\mathcal{L}(x|S_{sim})}{\mathcal{L}(x|B_{sim})}$$

x: some set of relevant features characterizing each event (almost always binned)

S: a *specific* signal model, e.g. supersymmetry



Model specific searches

$$R_S(x) = \frac{\mathcal{L}(x|S_{sim})}{\mathcal{L}(x|B_{sim})}$$

Rely on simulations of background and signal to construct likelihood ratio.

If simulations are sufficiently accurate (generally not the case!), then optimal for specific S by Neyman-Pearson Lemma x: some set of relevant features characterizing each event (almost always binned)

S: a *specific* signal model, e.g. supersymmetry



The most common approach: Model specific searches

signal and background model dependent

$$R_S(x) = \frac{\mathcal{L}(x|S_{sim})}{\mathcal{L}(x|B_{sim})}$$

Rely on simulations of background and signal to construct likelihood ratio.

If simulations are sufficiently accurate (generally not the case!), then optimal for specific S by Neyman-Pearson Lemma x: some set of relevant features characterizing each event (almost always binned)

S: a *specific* signal model, e.g. supersymmetry



The most common approach: Model specific searches

signal and background model dependent

$$R_S(x) = \frac{\mathcal{L}(x|S_{sim})}{\mathcal{L}(x|B_{sim})}$$

Rely on simulations of background and signal to construct likelihood ratio.

If simulations are sufficiently accurate (generally not the case!), then optimal for specific S by Neyman-Pearson Lemma x: some set of relevant features characterizing each event (almost always binned)

S: a *specific* signal model, e.g. supersymmetry



> 99% of searches at the LHC are of this type

Current Status of NP Searches @ LHC

ATLAS SUSY Searches* - 95% CL Lower Limits

Julv 2019 $\sqrt{s} = 13 \text{ TeV}$ Signature $\int \mathcal{L} dt \, [\text{fb}^{-1}]$ Model Mass limit Reference 1.55 0 e, µ 2-6 jets 36.1 m(X10)<100 GeV 1712.02332 $\tilde{q}\tilde{q}, \tilde{q} \rightarrow q\tilde{\chi}_1^0$ E_T^{T} 0.9 1-3 jets [1x, 8x Degen 0.43 mono-iet 1711.03301 36.1 0.71 $m(\tilde{q})-m(\tilde{\chi}_1^0)=5 \text{ GeV}$ Inclusive Searches $m(\tilde{\chi}_{1}^{0})$ <200 GeV 0 e, µ 2-6 jets E_T^{miss} 36.1 1712.02332 2.0 $\tilde{g}\tilde{g}, \tilde{g} \rightarrow q\bar{q}\tilde{\chi}_{1}^{0}$ 0.95-1.6 Forbidden $m(\tilde{\chi}_1^0)=900 \text{ GeV}$ 1712.02332 3 e, µ $m(\tilde{\chi}_1^0) < 800 \, GeV$ 4 jets 1706.03731 $\tilde{g}\tilde{g}, \tilde{g} \rightarrow q\bar{q}(\ell\ell)\tilde{\chi}_1^0$ 36.1 1.85 ee,µµ 2 jets E_T^{miss} 36.1 1.2 $m(\tilde{g})-m(\tilde{\chi}_1^0)=50 \text{ GeV}$ 1805.11381 0 e, µ $\tilde{g}\tilde{g}, \tilde{g} \rightarrow qqWZ\tilde{\chi}_1^0$ 7-11 jets E_T^{miss} 36.1 m(X10 <400 GeV 1.8 1708.02794 SS e, μ 6 jets 1.15 ATLAS-CONF-2019-015 139 $m(\tilde{g})-m(\tilde{\chi}_{1}^{0})=200 \text{ GeV}$ $\tilde{g}\tilde{g}, \tilde{g} \rightarrow t\bar{t}\tilde{\chi}_1^0$ 0-1 e, µ 3b E_T^{miss} 79.8 2.25 m(X10)<200 GeV ATLAS-CONF-2018-041 SS e, µ 6 jets 1.25 $m(\tilde{g})-m(\tilde{\chi}_1^0)=300 \text{ GeV}$ ATLAS-CONF-2019-015 139 Multiple 1708.09266, 1711.03301 $\tilde{b}_1 \tilde{b}_1, \tilde{b}_1 \rightarrow b \tilde{\chi}_1^0 / t \tilde{\chi}_1^{\pm}$ 36.1 Forbidden 0.9 $m(\tilde{\chi}_{1}^{0})=300 \text{ GeV}, BR(b\tilde{\chi}_{1}^{0})=1$ Multiple Forbidden 0.58-0.82 $m(\tilde{\chi}_{1}^{0})=300 \text{ GeV}, BR(b\tilde{\chi}_{1}^{0})=BR(t\tilde{\chi}_{1}^{\pm})=0.5$ 1708.09266 36.1 Multiple Forbidden 0.74 ATLAS-CONF-2019-015 139 Đ1 $m(\tilde{\chi}_{1}^{0})=200 \text{ GeV}, m(\tilde{\chi}_{1}^{\pm})=300 \text{ GeV}, BR(t\tilde{\chi}_{1}^{\pm})=1$ $\tilde{b}_1 \tilde{b}_1, \tilde{b}_1 \rightarrow b \tilde{\chi}_2^0 \rightarrow b h \tilde{\chi}_1^0$ 0 e, µ E_T^{miss} 139 0.23-1.35 $\Delta m(\tilde{\chi}_2^0, \tilde{\chi}_1^0) = 130 \text{ GeV}, m(\tilde{\chi}_1^0) = 100 \text{ GeV}$ SUSY-2018-31 6bõ1 Forbidden 0.23-0.48 Ď1 $\Delta m(\tilde{\chi}_2^0, \tilde{\chi}_1^0) = 130 \text{ GeV}, m(\tilde{\chi}_1^0) = 0 \text{ GeV}$ SUSY-2018-31 $\tilde{t}_1 \tilde{t}_1, \tilde{t}_1 \rightarrow W b \tilde{\chi}_1^0$ or $t \tilde{\chi}_1^0$ 1506.08616, 1709.04183, 1711.11520 0-2 e, µ 0-2 jets/1-2 b E_T^{miss} 36.1 1.0 $m(\tilde{\chi}_{1}^{0})=1 \text{ GeV}$ $\tilde{t}_1 \tilde{t}_1, \tilde{t}_1 \rightarrow Wb \tilde{\chi}_1^0$ 3 jets/1 b E_Tmiss 0.44-0.59 ATLAS-CONE-2019-017 1 e, µ 139 m(X10)=400 GeV $\tilde{t}_1\tilde{t}_1, \tilde{t}_1 \rightarrow \tilde{\tau}_1 bv, \tilde{\tau}_1 \rightarrow \tau \tilde{G}$ $1\tau + 1e,\mu,\tau$ m(~~1)=800 GeV 2 jets/1 b E_T^{miss} 36.1 1803.10178 1.16 $\tilde{t}_1 \tilde{t}_1, \tilde{t}_1 \rightarrow c \tilde{\chi}_1^0 / \tilde{c} \tilde{c}, \tilde{c} \rightarrow c \tilde{\chi}_1^0$ 0.85 $m(\tilde{\chi}_{1}^{0})=0$ GeV 0 e, µ 2 c E_T^{miss} 36.1 1805.01649 0.46 $m(\tilde{t}_1,\tilde{c})-m(\tilde{\chi}_1^0)=50 \text{ GeV}$ 1805.01649 0.43 $0 e. \mu$ mono-jet E_{π}^{n} 36.1 1711.03301 $m(\tilde{t}_1, \tilde{c}) - m(\tilde{\chi}_1^0) = 5 \text{ GeV}$ $\tilde{l}_2 \tilde{l}_2, \tilde{l}_2 \rightarrow \tilde{l}_1 + h$ 1-2 e, µ 4 b E_T^{miss} 36.1 0.32-0.88 $m(\tilde{\chi}_{1}^{0})=0 \text{ GeV}, m(\tilde{\iota}_{1})-m(\tilde{\chi}_{1}^{0})=180 \text{ GeV}$ 1706.03986 $\tilde{t}_2 \tilde{t}_2, \tilde{t}_2 \rightarrow \tilde{t}_1 + Z$ 3 e, µ 1 b E_T^m 139 Forbidden 0.86 $m(\tilde{\chi}_1^0)=360 \text{ GeV}, m(\tilde{t}_1)-m(\tilde{\chi}_1^0)=40 \text{ GeV}$ ATLAS-CONF-2019-016 \tilde{l}_2 $\tilde{\chi}_1^{\pm} / \tilde{\chi}_2^0$ $\tilde{\chi}_1^{\pm} / \tilde{\chi}_2^0$ $\tilde{\chi}_1^{\pm} \tilde{\chi}_2^0$ via WZ 2-3 e, µ E_T^{miss} 0.6 1403.5294, 1806.02293 36.1 $m(\tilde{\chi}_{1}^{0})=0$ E_T^{T} 0.205 ee,µµ ≥ 1 139 $m(\tilde{\chi}_1^{\pm})-m(\tilde{\chi}_1^0)=5 \text{ GeV}$ ATLAS-CONE-2019-014 $\tilde{\chi}_1^{\pm} \tilde{\chi}_1^{\mp}$ via WW 2 e, µ E_T^{miss} 139 0.42 ATLAS-CONF-2019-008 $m(\tilde{\chi}_{1}^{0})=0$ 2 b/2 γ 0-1 e,µ $\tilde{\chi}_1^{\pm} \tilde{\chi}_2^0$ via Wh 139 $\tilde{\chi}_1^{\pm}/\tilde{\chi}_2^0$ 0.74 ATLAS-CONF-2019-019, ATLAS-CONF-2019-XYZ E_T^{miss} Forbidden m($\tilde{\chi}_{1}^{0}$)=70 GeV $\tilde{\chi}_{1}^{\pm}\tilde{\chi}_{1}^{\mp}$ via $\tilde{\ell}_{L}/\tilde{\nu}$ E_T^{miss} 2 e, µ 139 ATLAS-CONF-2019-008 1.0 $m(\tilde{\ell}, \tilde{\nu}) = 0.5(m(\tilde{\chi}_{1}^{+}) + m(\tilde{\chi}_{1}^{0}))$ $\tilde{\tau}\tilde{\tau}, \tilde{\tau} \rightarrow \tau \tilde{\chi}_1^0$ 2τ E_T^{miss} 139 $[\tilde{\tau}_L, \tilde{\tau}_{R,L}]$ 0.16-0.3 0.12-0.39 ATLAS-CONF-2019-018 $m(\tilde{\chi}_{1}^{0})=0$ E_T^{miss} E_T^{miss} $\tilde{\ell}_{L,R}\tilde{\ell}_{L,R}, \tilde{\ell} \rightarrow \ell \tilde{\chi}_1^0$ $2 e, \mu$ 0 jets 139 0.7 ATLAS-CONF-2019-008 $m(\tilde{\chi}_{1}^{0})=0$ 0.256 $2 e, \mu$ ≥ 1 139 $m(\tilde{\ell})-m(\tilde{\chi}_1^0)=10 \text{ GeV}$ ATLAS-CONF-2019-014 E_T^{miss} E_T^{miss} $\tilde{H}\tilde{H}, \tilde{H} \rightarrow h\tilde{G}/Z\tilde{G}$ 0 e, µ 0.13-0.23 0.29-0.88 1806.04030 $\geq 3 b$ 36.1 ĨI $BR(\tilde{\chi}_{1}^{0} \rightarrow h\tilde{G})=1$ $4 e, \mu$ 0 jets 36.1 0.3 $BR(\tilde{\chi}_{1}^{0} \rightarrow Z\tilde{G})=1$ 1804.03602 Ĥ Direct $\tilde{\chi}_1^+ \tilde{\chi}_1^-$ prod., long-lived $\tilde{\chi}_1^+$ Disapp. trk 1 jet E_T^{miss} 0.46 Pure Wino 1712.02118 36.1 řŧ 0.15 Pure Higgsino ATL-PHYS-PUB-2017-019 Stable g R-hadron Multiple 36.1 2.0 1902.01636.1808.04095 Multiple 2.05 2.4 1710.04901.1808.04095 Metastable \tilde{g} R-hadron, $\tilde{g} \rightarrow qq \tilde{\chi}_1^0$ 36.1 $[\tau(\tilde{g}) = 10 \text{ ns}, 0.2 \text{ ns}]$ $m(\bar{\chi}_{1}^{0})=100 \text{ GeV}$ LFV $pp \rightarrow \tilde{v}_{\tau} + X, \tilde{v}_{\tau} \rightarrow e\mu/e\tau/\mu\tau$ λ'₃₁₁=0.11, λ_{132/133/233}=0.07 εμ,ετ,μτ 3.2 1.9 1607.08079 $\tilde{\chi}_1^+ \tilde{\chi}_1^{\mp} / \tilde{\chi}_2^0 \to WW/Z\ell\ell\ell\ell\nu\nu$ 0.82 1.33 $4 e, \mu$ 0 jets E_T^{miss} 36.1 m(X10)=100 GeV 1804.03602 $[\lambda_{i33} \neq 0, \lambda_{12k} \neq 0]$ $\tilde{g}\tilde{g}, \tilde{g} \rightarrow qq\tilde{\chi}_1^0, \tilde{\chi}_1^0 \rightarrow qqq$ 4-5 large-R jets 36.1 1.9 Large λ_{112}'' 1804.03568 1.3 ′)=200 GeV, 1100 GeV] ₌2e-4, 2e-5] 1.05 Multiple 36.1 2.0 $m(\tilde{\chi}_1^0)=200$ GeV, bino-like ATLAS-CONF-2018-003 RPV $\tilde{t}\tilde{t}, \tilde{t} \rightarrow t\tilde{\chi}_1^0, \tilde{\chi}_1^0 \rightarrow tbs$ Multiple 36.1 =2e-4, 1e-2 0.55 1.05 ATLAS-CONF-2018-003 $m(\tilde{\chi}_1^0)=200$ GeV, bino-like $\tilde{t}_1 \tilde{t}_1, \tilde{t}_1 \rightarrow bs$ 2 jets + 2 b 36.7 0.42 0.61 1710.07171 $\tilde{t}_1 \tilde{t}_1, \tilde{t}_1 \rightarrow q\ell$ 2 e, µ 2b36.1 $BR(\tilde{t}_1 \rightarrow be/b\mu) > 20\%$ 1710.05544 0.4-1.45 e-10< 1' <1e-8. 3e-10< 1' <3e-9 $BR(\tilde{t}_1 \rightarrow a\mu) = 100\%, \cos\theta = 1$ DV 136 1.0 1.6 ATLAS-CONF-2019-006 1μ

*Only a selection of the available mass limits on new states or

10⁻¹

Mass scale [TeV]

1

ATLAS Preliminary

Current Status of NP Searches @ LHC



*Only a selection (

Selection of observed limits at 95% C.L. (theory uncertainties are not included). Probe **up to** the quoted mass limit for light LSPs unless stated otherwise. The quantities ΔM and x represent the absolute mass difference between the primary sparticle and the LSP, and the difference between the intermediate

Current Status of NP Searches @ LHC



Vector-like quark single production



= 100% T doublet T singlet = 100% = 100%) = 100%Q doublet Q singlet = 100% = 100% = 100% 0.0 IEP 2019 Selection of observed limits at 95% C.L. The quantities ΔM and x represent the a sparticle and the LSP relative to ΔM , re $BB \rightarrow (l^{\pm}, l^{\pm}l^{\pm})$

→ tW(LH)

tW(RH)

) = 100%

B doublet

B singlet

= 100%

= 100%

Vector-like quark single production



$$R(x) = \frac{\mathcal{L}(x|data)}{\mathcal{L}(x|B_{sim})}$$

$$R(x) = \frac{\mathcal{L}(x|data)}{\mathcal{L}(x|B_{sim})}$$

x: a single feature (almost always binned)

Idea: compare data vs *simulated* SM background in ID histograms.

fully signal model independent background model dependent

$$R(x) = \frac{\mathcal{L}(x|data)}{\mathcal{L}(x|B_{sim})}$$

x: a single feature (almost always binned)

Idea: compare data vs *simulated* SM background in ID histograms.

fully signal model independent background model dependent

$$R(x) = \frac{\mathcal{L}(x|data)}{\mathcal{L}(x|B_{sim})}$$

x: a single feature (almost always binned)

Idea: compare data vs *simulated* SM background in ID histograms.

[Can also imagine turbocharged version: train DNN on full phase space to distinguish data from background MC (D'Agnolo, Wulzer et al 1806.02350, 1912.12155)]

fully signal model independent background model dependent

$$R(x) = \frac{\mathcal{L}(x|data)}{\mathcal{L}(x|B_{sim})}$$

x: a single feature (almost always binned)

Idea: compare data vs *simulated* SM background in ID histograms.

[Can also imagine turbocharged version: train DNN on full phase space to distinguish data from background MC (D'Agnolo, Wulzer et al 1806.02350, 1912.12155)]

Data vs bg likelihood ratio: not optimal for any specific signal, but could be optimal for rejecting background hypothesis.

fully signal model independent background model dependent

$$R(x) = \frac{\mathcal{L}(x|data)}{\mathcal{L}(x|B_{sim})}$$

x: a single feature (almost always binned)

Idea: compare data vs *simulated* SM background in ID histograms.

[Can also imagine turbocharged version: train DNN on full phase space to distinguish data from background MC (D'Agnolo, Wulzer et al 1806.02350, 1912.12155)]

Data vs bg likelihood ratio: not optimal for any specific signal, but could be optimal for rejecting background hypothesis.

Long but somewhat neglected history of searches of this type

Previous model-independent approaches

A brief history of model independent searches in HEP:

•	DO	"Sleuth"	PRD 64:012004 (2000) PRD 64:012004 (2001) PRL 86:3712 (2001)
•	HI (Hera)	"General Search"	PLB 602:14-30 (2004) 0705.3721
•	CDF	"Sleuth/Vista"	0712.1311 PRD 78:012002 (2008) 0712.2534 (submitted to PRL, NEVER PUBLISHED) 0809.3781 PRD 79:011101 (2009)
•	CMS	"MUSIC"	CMS-PAS-EXO-14-016
•	ATLAS	"Model independent general search"	1807.07447 EPJC 79:120 (2019)

DDD (2),002004 (2000)

An example of what is found



From B. Knuteson talk at UMich (2008)

Previous model-independent approaches "the bump hunt"

partially signal and background model independent

$$R(m) = \frac{\mathcal{L}(m|data)}{\mathcal{L}(m|B_{data})}$$

m: a single feature

Idea: assume signal is localized in m while background is smooth.

Use **sidebands** $m \notin (m0-\delta m, m0+\delta m)$ to interpolate background into **signal region** $m \in (m0-\delta m, m0+\delta m)$.

Classic method, used in many discoveries

Previous model-independent approaches "the bump hunt"



Higgs, Z, ...

Previous model-independent approaches

"the bump hunt"



Also a classic search for new physics — e.g. a hypothetical heavy BSM particle that decays to pairs of jets

Overview of search strategies





 $log(p_{background}(x|m))$



Searching for NP with deep autoencoders

Heimel et al 1808.08979; Farina, Nakai & DS 1808.08992



An autoencoder maps an input into a reduced "latent representation" and then attempts to reconstruct the original input from it.

Can use reconstruction error as an anomaly threshold!

See also: Hajer et al "Novelty Detection Meets Collider Physics" 1807.10261 Cerri et al "Variational Autoencoders for New Physics Mining at the Large Hadron Collider" 1811.10276


background (QCD)



Performance

It works as an anomaly detector!



Robust against contamination with signal — can use in fully unsupervised mode

Background estimation

Discriminant is useless without an accurate background prediction.

One idea: combine autoencoder with a bump hunt in jet mass. Estimate backgrounds using sidebands in mass.

Only works if cutting on reconstruction error does not sculpt the mass distribution of the background!



Bump hunt with autoencoder



We found empirically that the background jet mass distribution is fairly stable against cuts on CNN AE reconstruction loss above ~250 GeV.

Autoencoder with explicit decorrelation

A more controlled approach to mass decorrelation would be to explicitly penalize correlations in the training of the autoencoder.

One promising method: autoencoder with adversarial decorrelation (Heimel et al 1808.08979; based on 1611.01046, 1703.03507)

- Introduce a second NN, the adversary, that tries to predict the mass from the reconstruction loss.
- Penalize the total loss function when the adversary does well.

$$L_{adv} = \sum_{i} (f_{adv}(L_{AE}(x_i)) - m_i)^2$$
$$L_{tot} = L_{AE} - \lambda L_{adv}$$

See Tilman's talk for more on this (?)

Alternatives to adversaries

Adversaries are notoriously tricky to train — saddle point optimization

$$\min_{\theta_{\rm clf}} \max_{\theta_{\rm adv}} L_{\rm clf}(y(\theta_{\rm clf})) - \lambda L_{\rm adv}(y(\theta_{\rm clf}), m; \theta_{\rm adv})$$

Would be great if we could achieve the same performance but with a convex regularizer term

$$\min_{\theta_{\rm clf}} L_{\rm clf}(y(\theta_{\rm clf})) + \lambda C_{\rm reg}(y(\theta_{\rm clf}), m)$$

First idea: can we just use Pearson correlation coefficient?

$$C_{\rm reg} = R(y,m) \propto \sum_i y_i m_i$$

Problem: this only measures linear correlations

Pearson correlation



y and m can be highly correlated yet R=0

Distance correlation ("DisCo")

Promising idea: "distance correlation" (Szekely, Rizzo, Bakirov 2007; Szekely & Rizzo 2009)

 $dCov^{2}(X,Y) = \langle |X - X'| |Y - Y'| \rangle + \langle |X - X'| \rangle \langle |Y - Y'| \rangle - 2\langle |X - X'| |Y - Y''| \rangle$

- Zero iff X,Y are independent; positive otherwise
- Computationally tractable
- Straightforward sample definition doesn't require binning

Distance correlation ("DisCo")



Disco is sensitive to nonlinear correlations!

State of the art: ATLAS study of various decorrelation methods in context of boosted W-tagging.



25

Andreas Søgaard / University of Edinburgh







DisCo decorrelation

Gregor Kasieczka & DS 2001.05310



We have seen that one way to turn an autoencoder into an actual NP search is to combine it with a bump hunt.

However, what the autoencoder finds is rather uncontrolled and there is no guarantee of optimality (even asymptotically).

Can we get more if we build in the bump hunt assumption from the outset?

A growing number of methods aim to enhance the bump hunt using additional features:



primary resonant feature (m)



some additional features

A growing number of methods aim to enhance the bump hunt using additional features:



primary resonant feature (m)

some additional features



Use deep learning to derive something approaching the **multidimensional** likelihood ratio, *directly from the data*

$$R(\vec{x}) = \frac{\mathcal{L}(\vec{x}|data; m \in SR)}{\mathcal{L}(\vec{x}|B_{data}; m \in SR)}$$

Cut on R>R_c, enhance the bump hunt!

Enhancing the bump hunt

3 new ideas

I. <u>CWoLa Hunting</u> Collins, Howe & Nachman 1805.02664, 1902.02634

Assume \vec{x} and m are completely independent

Enhancing the bump hunt 3 new ideas

I. <u>CWoLa Hunting</u> Collins, Howe & Nachman 1805.02664, 1902.02634

Assume \vec{x} and m are completely independent

Enhancing the bump hunt 3 new ideas

I. <u>CWoLa Hunting</u> Collins, Howe & Nachman 1805.02664, 1902.02634

Assume \vec{x} and m are completely independent

$$R_{CWoLa}(\vec{x}) = \frac{\mathcal{L}(\vec{x}|data; m \in SR)}{\mathcal{L}(\vec{x}|data; m \notin SR)}$$

Enhancing the bump hunt 3 new ideas

I. <u>CWoLa Hunting</u> Collins, Howe & Nachman 1805.02664, 1902.02634

Assume \vec{x} and m are completely independent

$$R_{CWoLa}(\vec{x}) = \frac{\mathcal{L}(\vec{x}|data; m \in SR)}{\mathcal{L}(\vec{x}|data; m \notin SR)}$$
$$\int (\vec{x}|data; m \in SR)$$

$$= \frac{\mathcal{L}(\vec{x}|aata, m \in SR)}{\mathcal{L}(\vec{x}|B_{data}; m \notin SR)}$$

I. <u>CWoLa Hunting</u> Collins, Howe & Nachman 1805.02664, 1902.02634

Assume \vec{x} and m are completely independent

$$R_{CWoLa}(\vec{x}) = \frac{\mathcal{L}(\vec{x}|data; m \in SR)}{\mathcal{L}(\vec{x}|data; m \notin SR)}$$
$$= \frac{\mathcal{L}(\vec{x}|data; m \in SR)}{\mathcal{L}(\vec{x}|B_{data}; m \notin SR)}$$
$$\mathcal{L}(\vec{x}|data; m \in SR)$$

$$= \frac{\mathcal{L}(\vec{x}|B_{data}; m \in SR)}{\mathcal{L}(\vec{x}|B_{data}; m \in SR)}$$

I. <u>CWoLa Hunting</u> Collins, Howe & Nachman 1805.02664, 1902.02634

Assume \vec{x} and m are completely independent

Train a classifier on \vec{x} to distinguish signal region and sideband. If the classifier is near-optimal, it will approach likelihood ratio

$$R_{CWoLa}(\vec{x}) = \frac{\mathcal{L}(\vec{x}|data; m \in SR)}{\mathcal{L}(\vec{x}|data; m \notin SR)}$$

$$= \frac{\mathcal{L}(\vec{x}|data; m \in SR)}{\mathcal{L}(\vec{x}|B_{data}; m \notin SR)}$$

$$= \frac{\mathcal{L}(\vec{x}|data; m \in SR)}{\mathcal{L}(\vec{x}|B_{data}; m \in SR)}$$

"Classification Without Labels"

2. <u>AnoDE: Anomaly Detection with Density Estimation</u> Nachman & DS 2001.04990

Directly learn the conditional probability densities from the data

 $\mathcal{L}(\vec{x}|data; m \in SR) \qquad \mathcal{L}(\vec{x}|data; m \notin SR) = \mathcal{L}(\vec{x}|B_{data}; m \notin SR)$

2. <u>AnoDE: Anomaly Detection with Density Estimation</u> Nachman & DS 2001.04990

Directly learn the conditional probability densities from the data

 $\mathcal{L}(\vec{x}|data; m \in SR) \qquad \qquad \mathcal{L}(\vec{x}|data; m \notin SR) = \mathcal{L}(\vec{x}|B_{data}; m \notin SR)$

interpolate in (x,m)

2. <u>AnoDE: Anomaly Detection with Density Estimation</u> Nachman & DS 2001.04990

Directly learn the conditional probability densities from the data

 $\mathcal{L}(\vec{x}|data; m \in SR) \qquad \qquad \mathcal{L}(\vec{x}|data; m \notin SR) = \mathcal{L}(\vec{x}|B_{data}; m \notin SR)$

interpolate in (x,m)

 $\mathcal{L}(\vec{x}|B_{data}; m \in SR)$

2. <u>AnoDE: Anomaly Detection with Density Estimation</u> Nachman & DS 2001.04990

Directly learn the conditional probability densities from the data

 $\mathcal{L}(\vec{x}|data; m \in SR) \qquad \qquad \mathcal{L}(\vec{x}|data; m \notin SR) = \mathcal{L}(\vec{x}|B_{data}; m \notin SR)$

interpolate in (x,m)

 $\mathcal{L}(\vec{x}|B_{data}; m \in SR)$

Construct the likelihood ratio:
$$R(\vec{x}) = \frac{\mathcal{L}(\vec{x}|data; m \in SR)}{\mathcal{L}(\vec{x}|B_{data}; m \in SR)}$$

2. <u>AnoDE: Anomaly Detection with Density Estimation</u> Nachman & DS 2001.04990

Directly learn the conditional probability densities from the data

 $\mathcal{L}(\vec{x}|data; m \in SR) \qquad \qquad \mathcal{L}(\vec{x}|data; m \notin SR) = \mathcal{L}(\vec{x}|B_{data}; m \notin SR)$

interpolate in (x,m)

 $\mathcal{L}(\vec{x}|B_{data}; m \in SR)$

Construct the likelihood ratio:
$$R(\vec{x}) = \frac{\mathcal{L}(\vec{x}|data; m \in SR)}{\mathcal{L}(\vec{x}|B_{data}; m \in SR)}$$

Recent breakthroughs in (neural) density estimation make this possible in high dimensions. We used conditional MAF (Papamakarios et al 1705.07057) but many other density estimators are possible

3. <u>SALAD: Simulation Assisted Likelihood-free Anomaly Detection</u> Andreassen, Nachman & DS 2001.05001

Simulations in HEP are very good but not good enough to directly compare against data. If we could reweight simulations to match data they would be much more useful!

• Train a classifier on data vs simulation in sidebands. If this classifier is nearoptimal, it will approach the likelihood ratio (1907.08209)

$$w(\vec{x}) = \frac{\mathcal{L}(\vec{x}|B_{data}, m \notin SR)}{\mathcal{L}(\vec{x}|B_{sim}, m \notin SR)}$$

- Interpolate into SR
- Using reweighted simulation, generate a sample that follows $\mathcal{L}(\vec{x}|B_{data}, m \in SR)$
- Train a classifier to distinguish data from this sample
- Obtain a discriminant that approaches

3. <u>SALAD: Simulation Assisted Likelihood-free Anomaly Detection</u> Andreassen, Nachman & DS 2001.05001

Simulations in HEP are very good but not good enough to directly compare against data. If we could reweight simulations to match data they would be much more useful!

• Train a classifier on data vs simulation in sidebands. If this classifier is nearoptimal, it will approach the likelihood ratio (1907.08209)

$$w(\vec{x}) = \frac{\mathcal{L}(\vec{x}|B_{data}, m \notin SR)}{\mathcal{L}(\vec{x}|B_{sim}, m \notin SR)}$$

- Interpolate into SR
- Using reweighted simulation, generate a sample that follows $\mathcal{L}(ec{x}|B_{data}, m \in SR)$
- Train a classifier to distinguish data from this sample
- Obtain a discriminant that approaches $R(\vec{x}) = \frac{\mathcal{L}(\vec{x}|data; m \in SR)}{\mathcal{L}(\vec{x}|B_{data}; m \in SR)}$

LHC Olympics 2020

To facilitate a meaningful comparison between different approaches and to spur the development of new ones, in April 2019, Gregor Kasieczka, Ben Nachman and I initiated an anomaly detection data challenge:



The LHC Olympics 2020

https://indico.cern.ch/event/809820/page/19002-lhcolympics2020

LHC Olympics 2020: Black Boxes

We prepared three black boxes of simulated data:

- I million events each
- 4-vectors of every reconstructed particle (hadron) in the event
- Particle ID, charge, etc not included
- Single R=1 jet trigger pT>1.2 TeV
- Black boxes are meant to be representative of actual data, meaning they are mostly background and may contain signals of new physics

In addition, a sample of IM QCD dijet events (produced with Pythia8 and Delphes3.4.1) was provided as a background sample.

https://doi.org/10.5281/zenodo.3547721

LHC Olympics 2020: R&D Dataset

Prior to the challenge, we also released a labeled R&D dataset consisting of IM QCD dijet events and 100k signal events



https://doi.org/10.5281/zenodo.2629072

LHC Olympics 2020: R&D Dataset



LHC Olympics 2020: R&D Dataset



Additional features: $x = (m_{J_1}, m_{J_2}, \tau_{21}^{J_1}, \tau_{21}^{J_2})$

Comparing CWoLa vs Autoencoders with LHCO R&D Dataset Pablo Martin, Ben Nachman & DS work in progress

• Test performance of both methods for different S/B ratios



 \Rightarrow CWoLa performs better at large cross sections

 \Rightarrow Autoencoder solid at very low cross sections

Complementary techniques!
Ben Nachman & DS 2001.04990



The method works! ANODE is sensitive to the signal!

Ben Nachman & DS 2001.04990



Can enhance the significance of the bump hunt by a factor of up to 7!

(For this feature set, the CWoLa independence assumptions are satisfied, and it outperforms ANODE. Shows the power of likelihood free methods.)

Ben Nachman & DS 2001.04990

Novel aspect of ANODE: can estimate backgrounds directly with $L(x|B_{data}; m \in SR)$



Ben Nachman & DS 2001.04990

Can also consider performance on a feature set which is not independent of m. We introduced artificial correlations just as proof of concept: $m_{J_{1,2}} \rightarrow m_{J_{1,2}} + c m_{JJ}$



ANODE is robust while CWoLa completely fails!

LHC Olympics 2020: Submission format

A p-value associated with the dataset having no new particles (null hypothesis).
Short answer text
As complete a description of the new physics as possible. For example: the masses and decay modes of all new particles (and uncertainties on those parameters).
Short answer text
How many signal events (+uncertainty) are in the dataset (before any selection criteria).
Short answer text
Please consider submitting plots or a Jupyter notebook! (these will be private and used only for the presentation / documentation at the end)

https://docs.google.com/forms/d/e/1FAIpQLScw323fa9qpLbdMvGtr2YeqcGTjE5Zm18-umIDiPIdi_cWxVA/viewform

Overview of submissions

- 10 groups submitted results on box 1
- 4 of these groups also submitted results on boxes 2 & 3
- A number of additional groups could not finish the challenge in time but got results on the R&D dataset
- 7 of these groups gave talks about their methods and results at the ML4Jets2020 conference

Overview of submissions

People tried both supervised and unsupervised methods.

Methods used included

- Autoencoders
- CWoLa hunting
- PCA outlier detection
- LSTM
- CNN+BDT

- variational RNNs for anti-QCD tagging
- density estimation
- biological neural network
- ...

Box 1

Signal: 834 events



We revealed the answer at the ML4Jets2020 conference in early January









A clear winner emerged:

Conditional density estimation for anomaly detection

George Stein, Uros Seljak, Biwei Dai, He Jia

BERKELEY CENTER for COSMOLOGICAL PHYSICS

Used the ANODE method with a novel density estimator!

Μ







In second place:

Tag N' Train



JOHNS HOPKINS

Used a combination of autoencoders and CWoLa hunting





LHCO2020: Summer Games

https://indico.desy.de/indico/event/25341/

Stay tuned for more on the LHCO 2020...

We will be organizing a 1-day mini-workshop on anomaly detection in Hamburg the Saturday before BOOST (July 18).

There the answers for Boxes 2 and 3 will be revealed.

We will also discuss plans for a community paper on new methods for anomaly detection and the LHCO2020.

Please come and join us!

Conclusions

These are exciting times for anomaly detection in HEP.

Many new approaches making use of unsupervised ML are being developed by theorists and experimentalists.

Model independent searches have a bright future at the LHC. Maybe this is how we will finally discover the new physics!

These methods also have potential applications beyond HEP. For example, ANODE is a completely general method for finding localized overdensities in high dimensional datasets. One can imagine many uses for such a method!

Thanks for your attention!

Anomaly Detection at the LHC

In the broader ML field, there are two types of anomaly detection

point outlier, out of sample anomaly, *"zero-background search"* collective outlier, population anomaly *"bump hunt"*





In the broader ML field, there are two types of anomaly detection

ARE



Anomaly Detection at the LHC

In the broader ML field, there are two types of anomaly detection

point outlier, out of sample anomaly, *"zero-background search"*

easy

collective outlier, population anomaly *"bump hunt"*

hard

ÀRE HERE

Background estimation is a key component of anomaly detection in HEP

Sample definitions

 Background: QCD jets (p_T: 800-900 GeV, |η|<1, anti-kt R=1)



- Signals:
 - All-hadronic tops
 - 400 GeV gluinos decaying via RPV

 We formed jet images in η and φ with a pixel resolution and intensity given by the calorimeter towers.





Heimel et al 1808.08979; Farina, Nakai & DS 1808.08992

Loss function for autoencoder: *I*

$$L = \frac{1}{N} \sum_{i=1}^{N} (x_i^{in} - x_i^{out})^2$$

Heimel et al 1808.08979; Farina, Nakai & DS 1808.08992

Loss function for autoencoder: $L = \frac{1}{N} \sum_{i=1}^{N} (x_i^{in} - x_i^{out})^2$



Heimel et al 1808.08979; Farina, Nakai & DS 1808.08992

Loss function for autoencoder: $L = \frac{1}{N} \sum_{i=1}^{N} (x_i^{in} - x_i^{out})^2$



Heimel et al 1808.08979; Farina, Nakai & DS 1808.08992





Heimel et al 1808.08979; Farina, Nakai & DS 1808.08992





Convolutional Autoencoder Autoencoder architecture



128C3-MP2-128C3-MP2-128C3-32N-6N-32N-12800N-128C3-US2-128C3-US2-1C3 128C3-MP2-128C3-MP2-128C3-32N-6N-32N-12800N-128C3-US2-128C3-US2-1C3

Our primary autoencoder used convolutional neural networks (CNNs) for encoding and decoding the jet images.

We also considered autoencoders based on PCA and simple DNNs.

Many more architectures are possible.

- d too large \rightarrow autoencoder becomes identity transform
- d too small \rightarrow autoencoder cannot learn all the features

- d too large \rightarrow autoencoder becomes identity transform
- d too small \rightarrow autoencoder cannot learn all the features



- d too large \rightarrow autoencoder becomes identity transform
- d too small \rightarrow autoencoder cannot learn all the features





- d too large \rightarrow autoencoder becomes identity transform
- d too small \rightarrow autoencoder cannot learn all the features





Performance: weakly supervised mode



Fully unsupervised mode

Can also train on QCD background "contaminated" with a small fraction of signal. This could be representative of actual data.



Performance of AE robust even up to 10% contamination!

Autoencoder with explicit decorrelation



Bump hunt with autoencoder



Train directly on data that contains 400 GeV gluinos. Use the AE to clean away QCD jets. Enhance the significance of the bump hunt! (improve S/B by factor of ~6)

Could really discover new physics this way!